

Orbital Angular Momentum: Symmetry and Conservation Law

Conservation of Orbital Angular Momentum

Let's say, we have a particle in a central force field. Take an origin of the coordinate as a center of the force, and position the particle as \mathbf{r} , then the vectors of the force can be expressed as $f(r)\mathbf{r}/r$. Given a mass of the particle as m , we can rewrite Newton's Equation on Motion:

$$m\ddot{\mathbf{r}} = f(r)\frac{\mathbf{r}}{r} \quad (1)$$

The dots on the variable represent a time-derivative. The time-derivative for the vector product $\mathbf{r} \times \dot{\mathbf{r}}$ according to (1) can be expressed as:

$$\frac{d}{dt}(\mathbf{r} \times \dot{\mathbf{r}}) = (\dot{\mathbf{r}} \times \dot{\mathbf{r}}) + (\mathbf{r} \times \ddot{\mathbf{r}}) = \frac{f(r)}{m} \frac{(\mathbf{r} \times \mathbf{r})}{r} = 0$$

Therefore, $\mathbf{r} \times \dot{\mathbf{r}}$ remains constant independent of time. The vectors that we consider are the angular momentum (orbital angular momentum) in classical mechanics. ($\mathbf{p} = m\dot{\mathbf{r}}$ is the momentum)

$$\vec{\ell} = \mathbf{r} \times m\dot{\mathbf{r}} = \mathbf{r} \times \mathbf{p} \quad (2)$$

The equation above shows that the angular momentum is kept constant on the particle where it moves within a central force field. The constant direction of $\vec{\ell}$ represents the position vector \mathbf{r} always stays on a one plane, which is perpendicular to $\vec{\ell}$. We can understand the meaning of a vector having constant magnitude, by simply following the steps: First, take $\vec{\ell}$ direction on z -axis and using two-dimension polar coordinates:

$$x = r \cos \phi, \quad y = r \sin \phi$$

Classic relational expression for $\ell_z = xp_y - yp_x$:

$$p_x = m\dot{r} \cos \phi - mr \sin \phi \dot{\phi}, \quad p_y = m\dot{r} \sin \phi + mr \cos \phi \dot{\phi}$$

We can derive:

$$\ell_z = mr^2 \frac{d\phi}{dt}$$

Accordingly, $\ell = \text{constant}$ (now we define $\ell_z = \text{constant}$) refers to the constant, which is independent of areal velocity $r^2 \frac{d\phi}{dt}$. We categorize angular momentum especially for the orbital to differentiate the spin angular momentum that is a purely quantum mechanic phenomenon without any analogy in classical mechanics.

The total angular momentum remains constant even when a system of particles interact with one another, and the vector of the force acting on in between the particles is parallel to the vector $\mathbf{r}_{ik} = \mathbf{r}_i - \mathbf{r}_k$. The total angular momentum \mathbf{L} is defined as the sum of the angular momentum of each particle with attachment i , which refers to the individual particle:

$$\mathbf{L} = \sum_i \mathbf{r}_i \times m\dot{\mathbf{r}}_i = \sum_i \mathbf{r}_i \times \mathbf{p}_i \quad (3)$$

Time derivative of (3) is:

$$\begin{aligned} \frac{d}{dt}\mathbf{L} &= \sum_i m\{(\dot{\mathbf{r}}_i \times \dot{\mathbf{r}}_i) + (\mathbf{r}_i \times \ddot{\mathbf{r}}_i)\} = \sum_i (\mathbf{r}_i \times \sum_k \mathbf{F}_{ik}) \\ &= \sum_{i>k} (\mathbf{r}_i - \mathbf{r}_k) \times \mathbf{F}_{ik} = 0 \end{aligned} \quad (4)$$

Above indicates that the total angular momentum is being conserved. \mathbf{F}_{ik} is the force acting on the particle i from the particle k , and the equation of motion can be written with applications of Newton's third law $\mathbf{F}_{ik} = -\mathbf{F}_{ki}$, and the fact of $\mathbf{r}_i - \mathbf{r}_k$ being parallel to \mathbf{F}_{ik} :

$$m\ddot{\mathbf{r}}_i = \sum_k \mathbf{F}_{ik}$$

In classical mechanics, the angular momentum is conserved when the particle moves in a central force field or when the particles are interacting with a force acting along a direction of the mutual position vectors,.

Orbital Angular Momentum Operator in Quantum Mechanics

The orbital angular momentum is defined by (2), hence we can rewrite (2) as an operator:

$$\begin{aligned} \hat{\mathbf{l}} = \mathbf{r} \times \hat{\mathbf{p}} &= \frac{\hbar}{i} \mathbf{r} \times \nabla = \frac{\hbar}{i} (y \frac{\partial}{\partial z} - z \frac{\partial}{\partial y}, z \frac{\partial}{\partial x} - x \frac{\partial}{\partial z}, x \frac{\partial}{\partial y} - y \frac{\partial}{\partial x}) \\ &= (\hat{\ell}_x, \hat{\ell}_y, \hat{\ell}_z) \end{aligned} \quad (5)$$

The component $\hat{\ell}_x$, when acted about the function $f(r)$, we can obtain:

$$\frac{\partial f(r)}{\partial x} = \frac{df(r)}{dr} \cdot \frac{\partial r}{\partial x} = \frac{x}{r} \cdot \frac{df(r)}{dr}$$

We can derive:

$$\hat{\ell}_x f(r) = -i\hbar(y \frac{\partial f(r)}{\partial z} - z \frac{\partial f(r)}{\partial y}) + f(r)\hat{\ell}_x = f(r)\hat{\ell}_x \quad (6a)$$

In the same way, we can also derive:

$$\hat{\ell}_y f(r) = f(r)\hat{\ell}_y, \quad \hat{\ell}_z f(r) = f(r)\hat{\ell}_z \quad (6b)$$

As we can see later on in (16), the above refers to the fact that $\hat{\ell}_x$ and others does not include the derivative $\partial/\partial r$ of the radial vector r in polar coordinates.

Now, take a look at the close relationship between the operators of the orbital angular momentum and Laplacian $\Delta = \nabla \cdot \nabla$. Apparently we can write out:

$$\begin{aligned} \hat{\ell}_x^2 &= \left(\frac{\hbar}{i}\right)^2 \left(y \frac{\partial}{\partial z} - z \frac{\partial}{\partial y}\right) \left(y \frac{\partial}{\partial z} - z \frac{\partial}{\partial y}\right) \\ &= -\hbar^2 \left(y^2 \frac{\partial^2}{\partial z^2} + z^2 \frac{\partial^2}{\partial y^2} - 2yz \frac{\partial^2}{\partial y \partial z} - y \frac{\partial}{\partial y} - z \frac{\partial}{\partial z}\right) \end{aligned}$$

Then,

$$\begin{aligned} &(\hat{\ell}_x^2 + \hat{\ell}_y^2 + \hat{\ell}_z^2)/\hbar^2 \\ &= -\left(y^2 \frac{\partial^2}{\partial z^2} + z^2 \frac{\partial^2}{\partial y^2} + z^2 \frac{\partial^2}{\partial x^2} + x^2 \frac{\partial^2}{\partial z^2} + x^2 \frac{\partial^2}{\partial y^2} + y^2 \frac{\partial^2}{\partial x^2}\right) \quad (7a) \\ &\quad + 2\left(yz \frac{\partial^2}{\partial y \partial z} + zx \frac{\partial^2}{\partial z \partial x} + xy \frac{\partial^2}{\partial x \partial y}\right) + 2\left(y \frac{\partial}{\partial y} + z \frac{\partial}{\partial z} + x \frac{\partial}{\partial x}\right) \end{aligned}$$

While it is:

$$\begin{aligned} r^2 \Delta &= (x^2 + y^2 + z^2) \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2}\right) \\ &= \left(x^2 \frac{\partial^2}{\partial x^2} + y^2 \frac{\partial^2}{\partial y^2} + z^2 \frac{\partial^2}{\partial z^2}\right) \\ &\quad + \left(y^2 \frac{\partial^2}{\partial z^2} + z^2 \frac{\partial^2}{\partial y^2} + z^2 \frac{\partial^2}{\partial x^2} + x^2 \frac{\partial^2}{\partial z^2} + x^2 \frac{\partial^2}{\partial y^2} + y^2 \frac{\partial^2}{\partial x^2}\right), \quad (7b) \end{aligned}$$

$$\begin{aligned} (\mathbf{r} \cdot \nabla)^2 &= \left(x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} + z \frac{\partial}{\partial z}\right)^2 \\ &= 2\left(xy \frac{\partial^2}{\partial x \partial y} + yz \frac{\partial^2}{\partial y \partial z} + zx \frac{\partial^2}{\partial z \partial x}\right) \quad (7c) \\ &\quad + \left(x^2 \frac{\partial^2}{\partial x^2} + y^2 \frac{\partial^2}{\partial y^2} + z^2 \frac{\partial^2}{\partial z^2}\right) + \left(x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} + z \frac{\partial}{\partial z}\right) \end{aligned}$$

In short, from (7a ~ c) we can derive:

$$\hat{\ell}^2/\hbar^2 = -r^2 \Delta + (\mathbf{r} \cdot \nabla)^2 + (\mathbf{r} \cdot \nabla) \quad (8)$$

This is equally formulated. We can also rewrite the Laplacian:

$$\Delta = \frac{1}{r^2}[(\mathbf{r} \cdot \nabla)^2 + (\mathbf{r} \cdot \nabla)] - \frac{1}{r^2 \hbar^2} \hat{\ell}^2 \quad (9)$$

Furthermore, to express $(\mathbf{r} \cdot \nabla)$ in polar coordinates (note (15) and the graph 6.1) we can also write:

$$\Delta = \frac{1}{r^2} \left(r \frac{\partial}{\partial r} \right)^2 + \frac{1}{r} \left(\frac{\partial}{\partial r} \right) - \frac{1}{r^2 \hbar^2} \hat{\ell}^2 = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \right) - \frac{1}{r^2 \hbar^2} \hat{\ell}^2 \quad (9')$$

As it is indicated in (6a~b), $\hat{\ell}$ does not include the derivatives of the radius vector component. We also obtain the fact that all the operators concerning with the angles θ, ϕ are included within the term $\hat{\ell}^2$ when Laplacian is in polar coordinates because we cannot observe θ, ϕ in any other terms but $\hat{\ell}^2$, as it shows in (9').

There is another essential relational expression to be derived. The commutator $[\hat{\ell}_\alpha, \hat{\ell}_\beta]$ is easily found out by using the definition (5):

$$\begin{aligned} & [\hat{\ell}_x, \hat{\ell}_y] \\ &= \left(\frac{\hbar}{i} \right)^2 \left\{ \left(y \frac{\partial}{\partial z} - z \frac{\partial}{\partial y} \right) \left(z \frac{\partial}{\partial x} - x \frac{\partial}{\partial z} \right) - \left(z \frac{\partial}{\partial x} - x \frac{\partial}{\partial z} \right) \left(y \frac{\partial}{\partial z} - z \frac{\partial}{\partial y} \right) \right\} \\ &= \left(\frac{\hbar}{i} \right)^2 \left\{ y \frac{\partial}{\partial x} - x \frac{\partial}{\partial y} \right\} = i \hbar \hat{\ell}_z. \end{aligned} \quad (10a)$$

In the same way, we can calculate the followings:

$$[\hat{\ell}_y, \hat{\ell}_z] = i \hbar \hat{\ell}_x, \quad [\hat{\ell}_z, \hat{\ell}_x] = i \hbar \hat{\ell}_y \quad (10b)$$

$$[\hat{\ell}_x, \hat{\ell}_x] = [\hat{\ell}_y, \hat{\ell}_y] = [\hat{\ell}_z, \hat{\ell}_z] = 0 \quad (10c)$$

For another expression we can write:

$$\begin{aligned} [\hat{\ell}_x, \Delta] &= \frac{\hbar}{i} \left\{ \left(y \frac{\partial}{\partial z} - z \frac{\partial}{\partial y} \right) \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) \right. \\ &\quad \left. - \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) \left(y \frac{\partial}{\partial z} - z \frac{\partial}{\partial y} \right) \right\} \\ &= \hat{\ell}_x \Delta - \Delta \hat{\ell}_x = 0. \end{aligned} \quad (11a)$$

In exactly the same way, we can derive:

$$[\hat{\ell}_y, \Delta] = [\hat{\ell}_z, \Delta] = 0 \quad (11b)$$

As we have already shown in above, there exist a relationship (9') between the Laplacian Δ and the sum of the square of the angular momentum operators. Moreover, \hat{l}_α does not include the derivative $\frac{\partial}{\partial r}$ of the radius vector component. Based on these facts, (11a~b) indicates:

$$[\hat{l}_x, \hat{l}^2] = [\hat{l}_y, \hat{l}^2] = [\hat{l}_z, \hat{l}^2] = 0 \quad (11c)$$

(11c) can be derived through the direct calculation of the commutators \hat{l}^2 and $\hat{l}_x, \hat{l}_y, \hat{l}_z$, also.